

# Beyond Human Data: Scaling Self-Training for Problem-Solving with Language Models

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# Introduction

- Large language models (LLMs) excel in various tasks but rely heavily on human-generated data.
- Human data is costly and scarce, especially for complex problem-solving tasks (e.g., math, coding).
- This paper proposes **ReST-EM**, a self-training method using expectation-maximization (EM) and reinforcement learning (RL) to reduce dependence on human data.
- Significance: Improves LLMs with minimal human input, leveraging scalar feedback.

# Related and Past Work

## **Expert Iteration (ExiT):**

Uses search/MCTS for expert sample generation, then distills into the base model. ReSTEM replaces search with temperature sampling.

## **Self-Taught Reasoner (STaR):**

Employs greedy decoding and rationalization, though rationalization may lead to false positives.

## **Rejection Sampling Fine-Tuning (RFT):**

Runs a single generate-and-improve cycle; shows limited gains on GSM8K versus ReSTEM's iterative gains on harder benchmarks.

## **Iterative Maximum Likelihood (IML):**

Optimizes via reward-weighted log-likelihood on mini-batches, risking overfitting and high computation cost.

## **RWR & RAFT:**

Apply EM with reward scaling or ranking. RAFT is similar to IML for binary rewards and aligns with ReSTEM.

# Comparison

	ReST <sup>EM</sup>	ReST	STaR	RFT
Starts from fine-tuned model	✗	✓	✗	✗
Finetunes from base model in each iteration	✓	✗	✓	N/A
Uses rationalizations for unsolved questions	✗	✗	✓	✗
Temperature sampling for exploration	✓	✓	✗	✓
Experiments with Large LMs	✓	✗	✗	✓
Multiple iterations	✓	✓	✓	✗
Larger gains on bigger models	✓	N/A	N/A	✗
Evaluation on held out tasks	✓	✗	✗	✗

# Problem Formulation

- Assume access to an autoregressive language model which can produce a sequence of output tokens  $\mathbf{y} = (y_1, y_2, \dots, y_T)$  given context or source input  $\mathbf{x} = (x_1, x_2, \dots, x_L)$ .
- Assuming that the model is parametrised by  $\theta$ , the conditional probability of generating a sequence  $\mathbf{y}$  given  $\mathbf{x}$  is:

$$p_{\theta}(\mathbf{y} | \mathbf{x}) = \prod_{t=1}^T p_{\theta}(y_t | y_{<t}, \mathbf{x})$$

- Assume access to deterministic sequence level (or terminal) reward  $r(\mathbf{x}, \mathbf{y})$
- Goal: Maximize  $\mathcal{L}_{RL}(\theta) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}} \left[ \mathbb{E}_{\mathbf{y} \sim p_{\theta}(\mathbf{y} | \mathbf{x})} [r(\mathbf{x}, \mathbf{y})] \right]$

# But ....

- Optimizing  $\mathcal{L}_{RL}(\theta) = \mathbb{E}_{\mathbf{x} \sim \mathcal{D}} \left[ \mathbb{E}_{y \sim p_{\theta}(\mathbf{y}|\mathbf{x})} [r(\mathbf{x}, \mathbf{y})] \right]$  is computationally expensive.
- Policy Gradient based RL methods require updating and sampling from the policy numerous times during training.

# Idea: Expectation Maximization

- Expectation Maximization (Dempster, A.P.; Laird, N.M.; Rubin, D.B. (1977) , Dayan & Hinton 1997)
- Define binary optimality variable  $O$ , such that  $p(O = 1 \mid \mathbf{x}, \mathbf{y}) \propto f(r(\mathbf{x}, \mathbf{y}))$
- We want to maximize the log likelihood of observing  $O = 1$  (obtaining high reward)
- $$\log(p(O = 1 \mid x)) := \log \sum_y p_{\theta}(\mathbf{y} \mid \mathbf{x}) p(O = 1 \mid \mathbf{x}, \mathbf{y})$$
- However, the sum over all possible output sequences  $\mathbf{y}$  is typically intractable.
- So, instead of maximising log likelihood directly, we maximize its Evidence Lower Bound.

# ELBO

- The Evidence Lower Bound for the log likelihood term is given by:
- $\mathcal{L}(p_\theta, q) = \mathbb{E}_{q(y|x)}[\log p(O = 1 | x, y)] - \text{KL}\left(q(y | x) \parallel p_\theta(y | x)\right)$
- The expectation maximization algorithm maximizes this objective by alternating between E-step and M-step.
- E-step:
  - $q^{t+1} = \operatorname{argmax}_q L(p_{\theta^t}, q)$
- M-step:
  - $\theta^{t+1} = \operatorname{argmax}_\theta L(p_\theta, q^{t+1})$

# ReSTEM

## Generate (E-step):

- **Input:** Current model  $p_\theta$ , dataset  $D$  of input contexts (e.g., math problems).
- **Process:**
  1. For each input  $x_j$  in  $D$ , sample  $N$  outputs  $y_j$  from  $p_\theta(y|x_j)$
  2. Score each pair  $(x_j, y_j)$  with a binary reward  $r(x_j, y_j)$ :
    - 1 if correct, 0 if incorrect.
  3. Collect correct pairs into a new dataset  $D_i = \{(x_j, y_j) | r(x_j, y_j) = 1\}$ .
- **Output:** A dataset  $D_i$  of high-quality (correct) samples.

# ReSTEM

- **Improve (M-step):**
- **Input:** Base pre-trained model  $\theta_{\text{base}}$ , dataset  $D_i$
- **Process:**
  - Fine-tune  $\theta_{\text{base}}$  on  $D_i$  to maximize:
    - $J(\theta) = \mathbb{E}_{(x,y) \sim \mathcal{D}_i} [r(x,y) \log p_{\theta}(y \mid x)]$
  - Since  $r(x,y)=1$  for all pairs in  $D_i$ , fine-tuning on correct outputs
- **Output:** A new model  $\theta_i$ , used for the next Generate step

# Experiment

## Tasks:

- Math: Hendrycks MATH, GSM8K
- Coding: APPS (Intro) & HumanEval

**Models:** PaLM-2 Series (S, S\*, L)

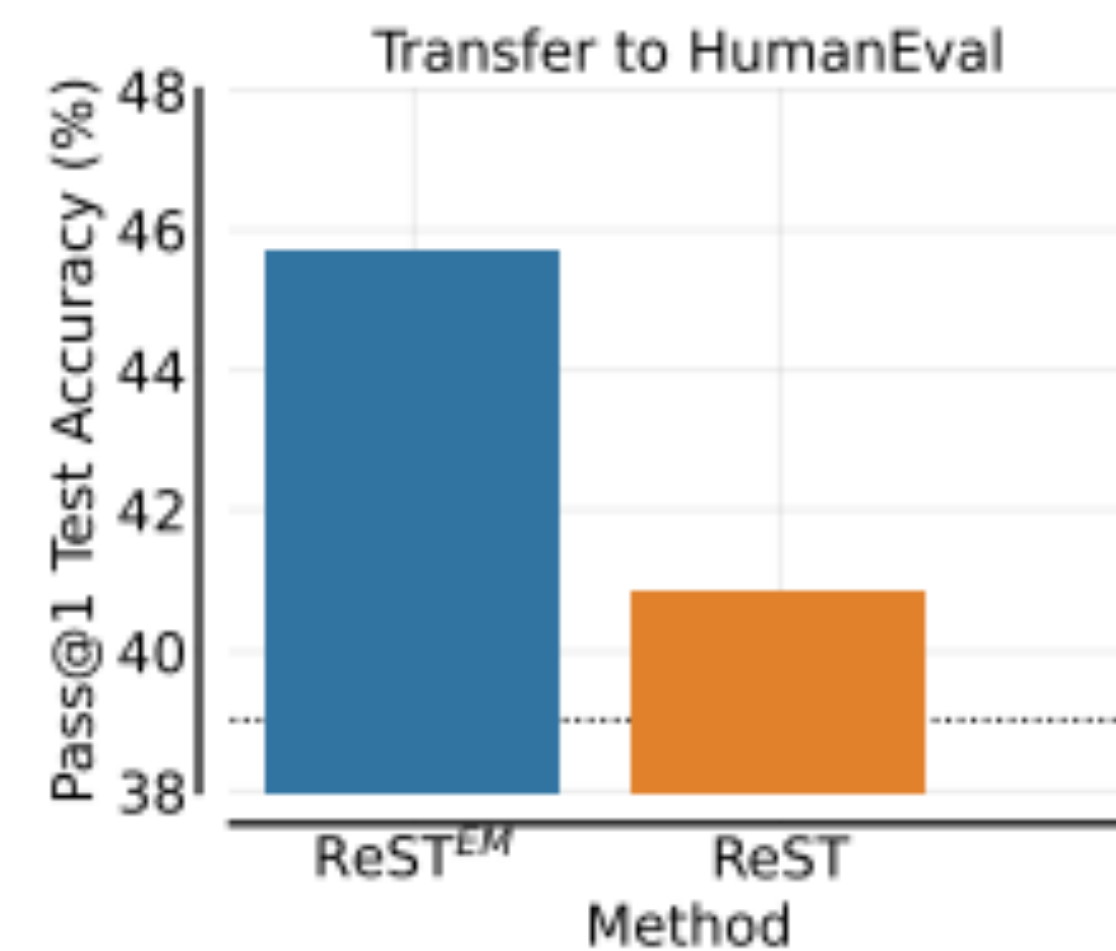
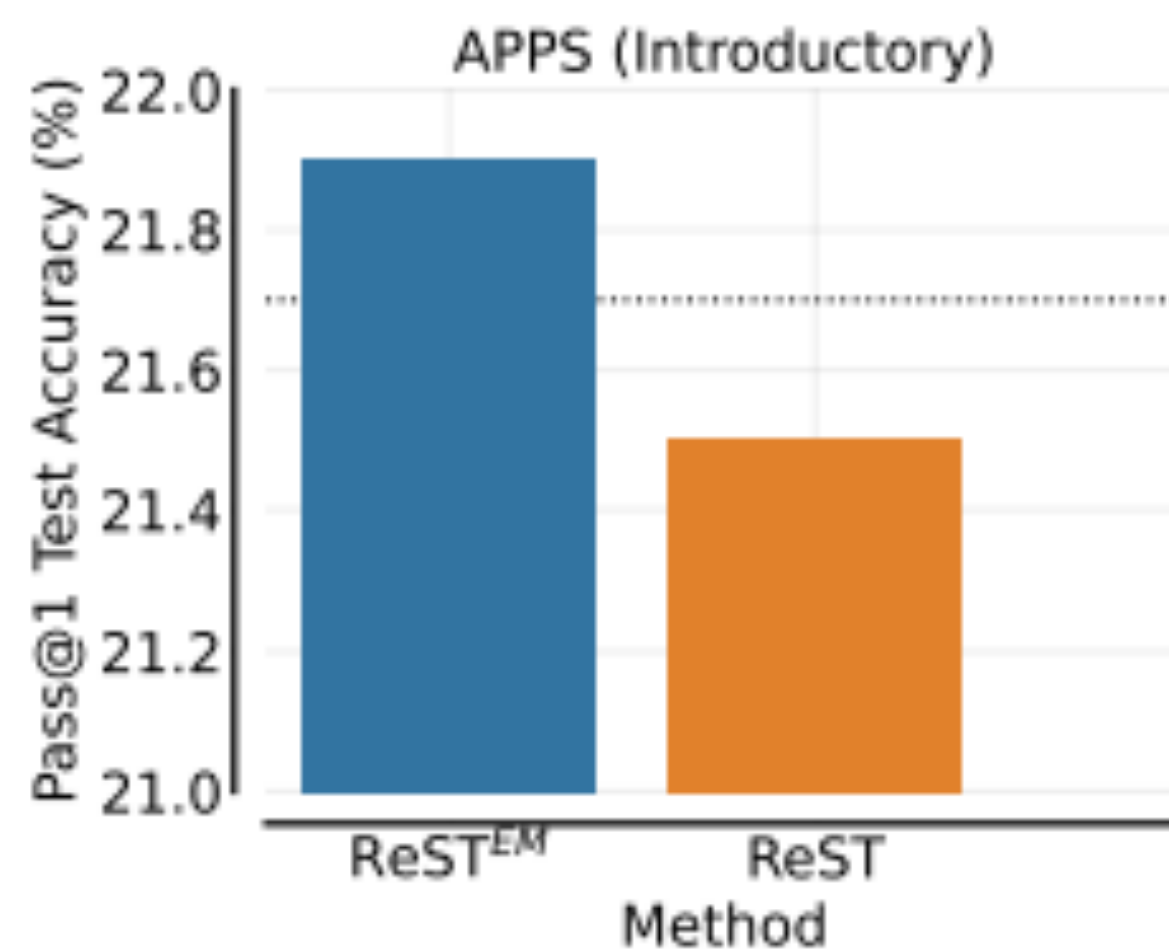
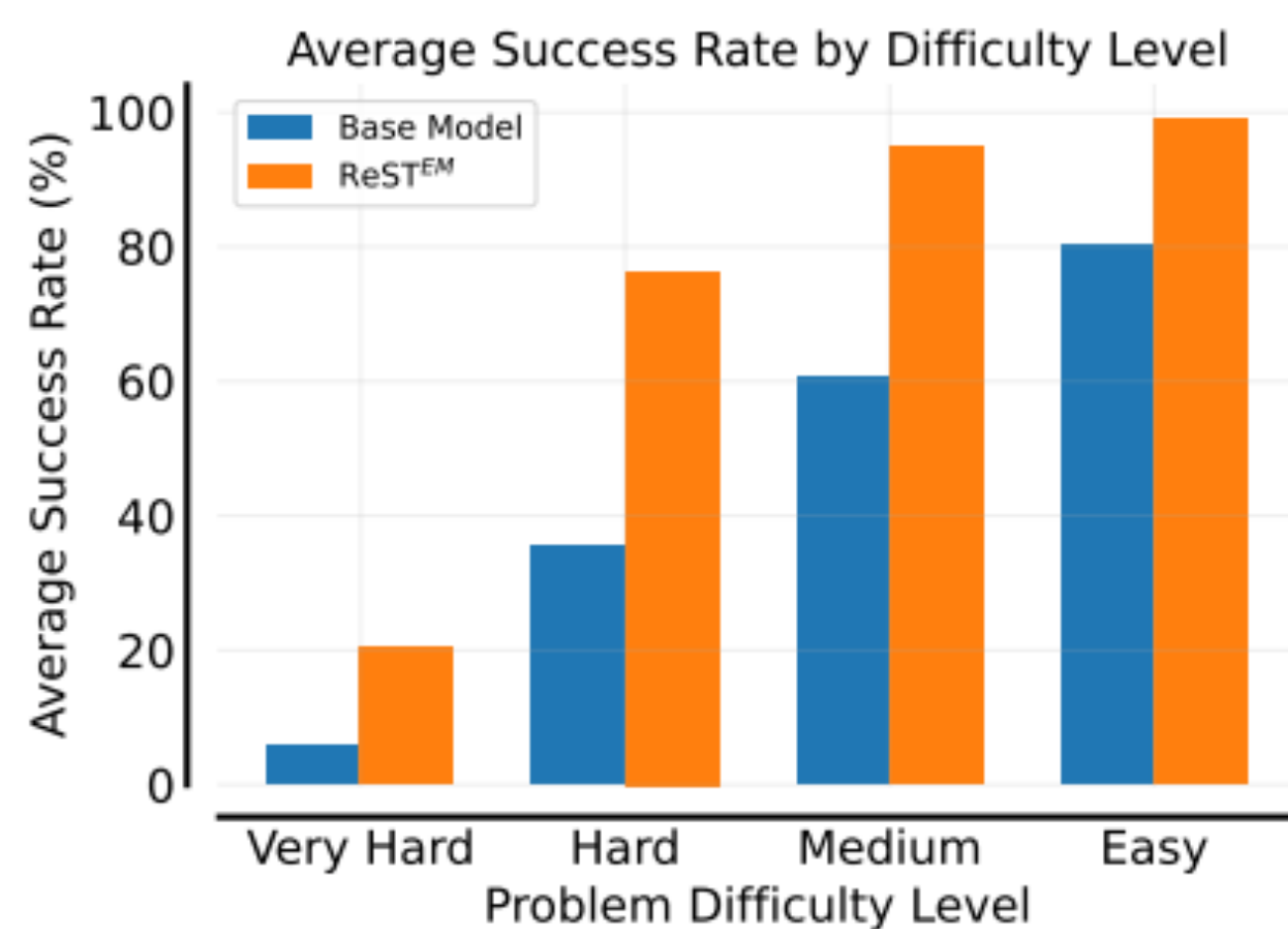
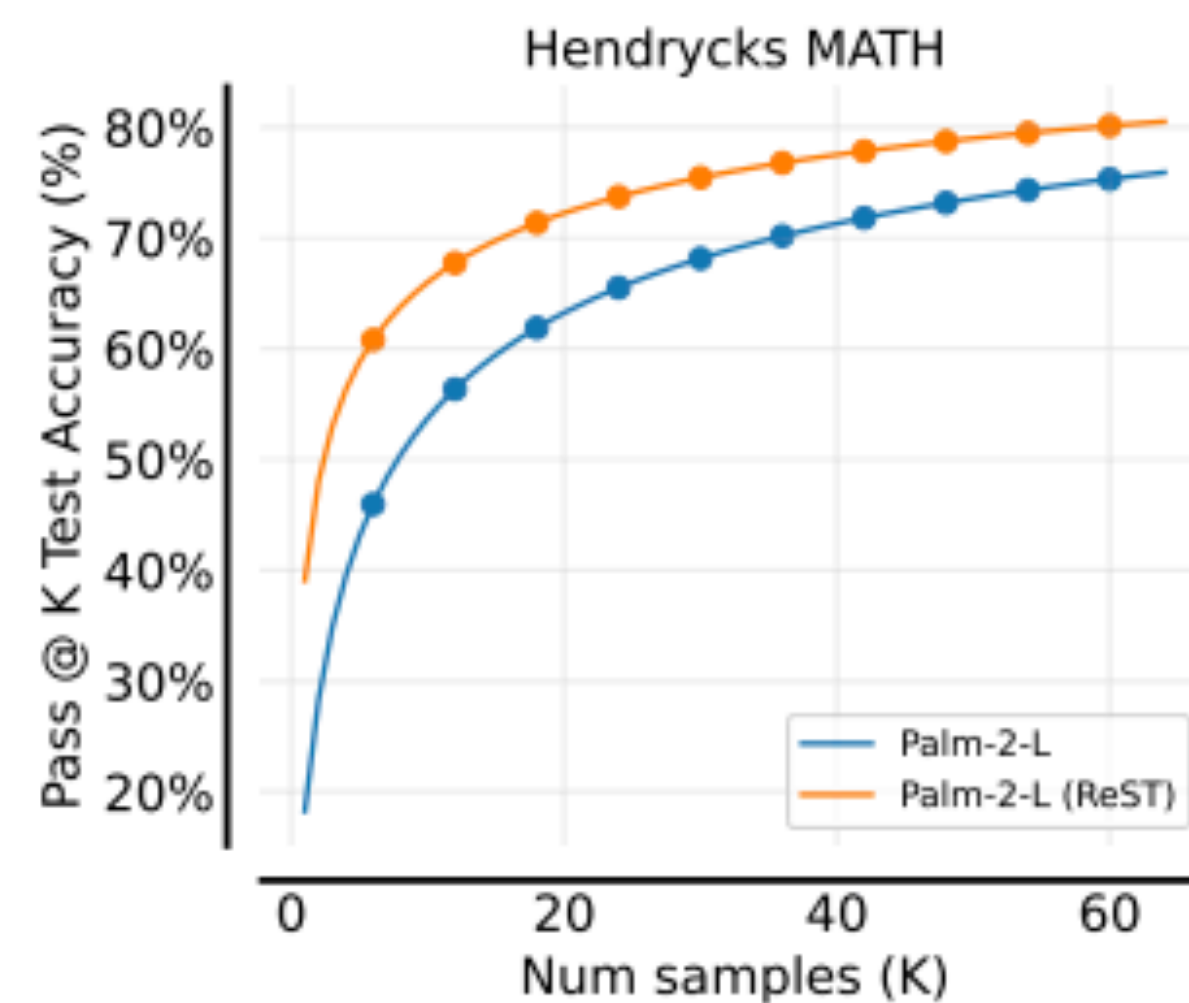
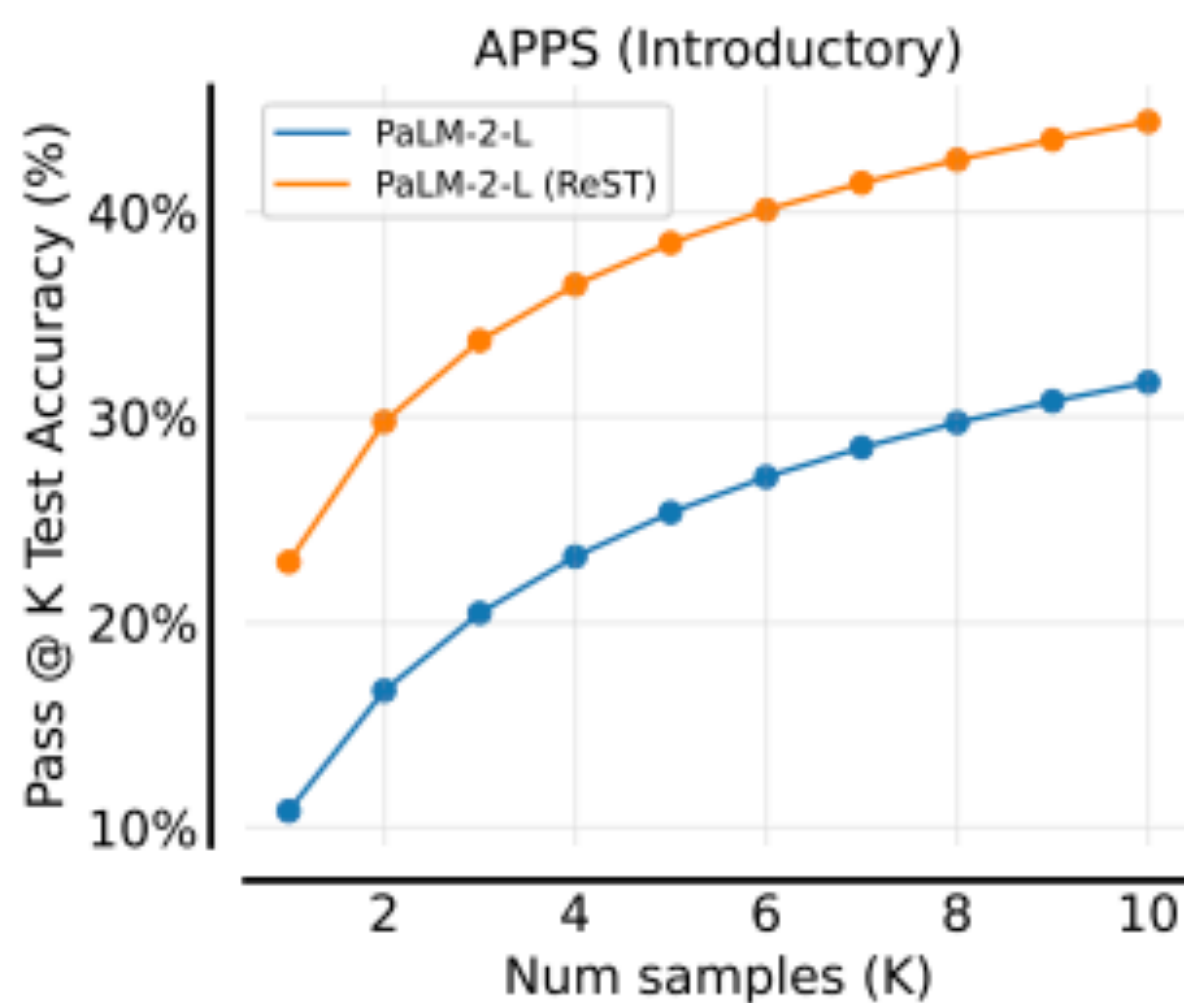
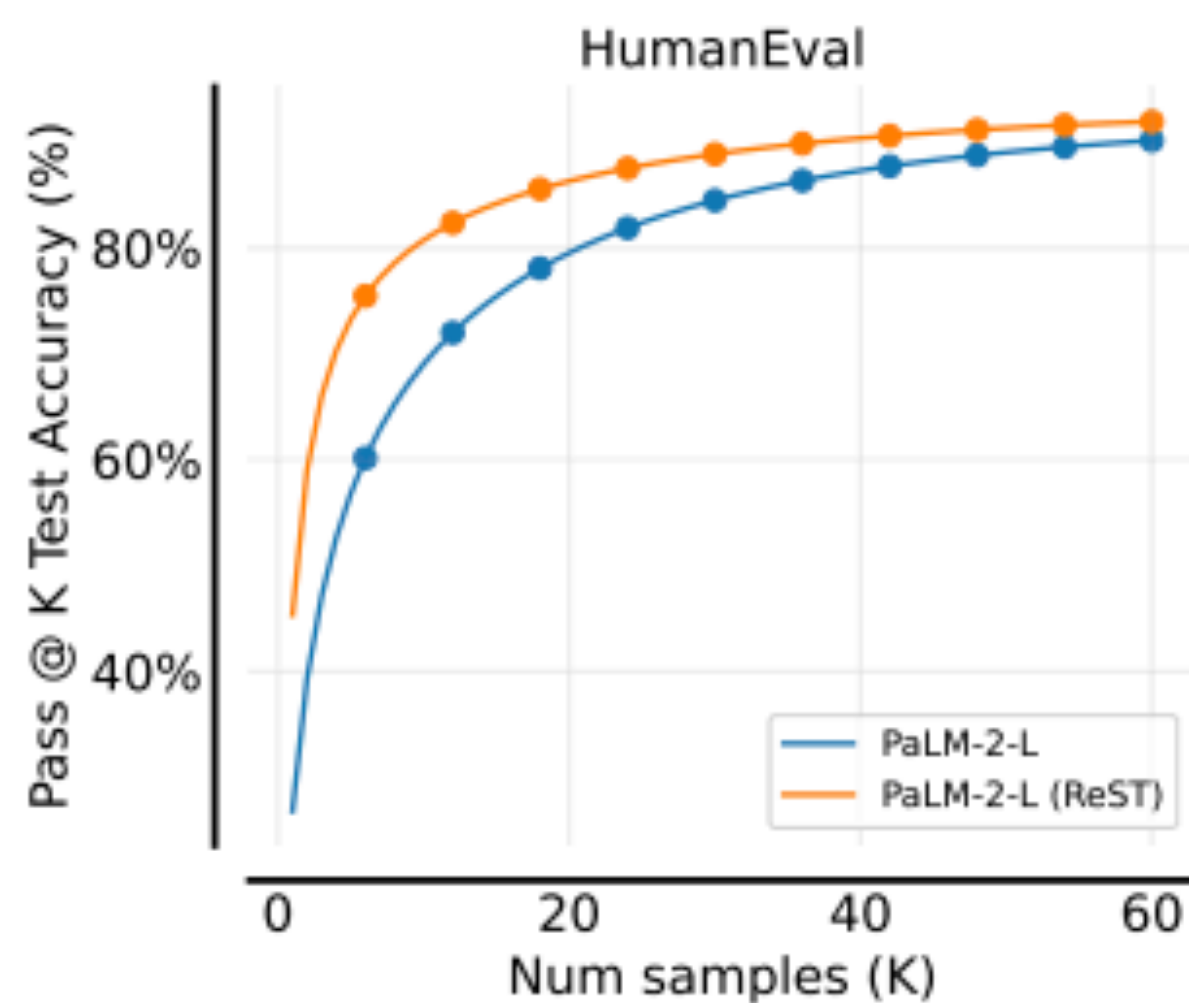
## Main Comparison:

- SFT on human data vs. ReST<sup>EM</sup> on model-generated data

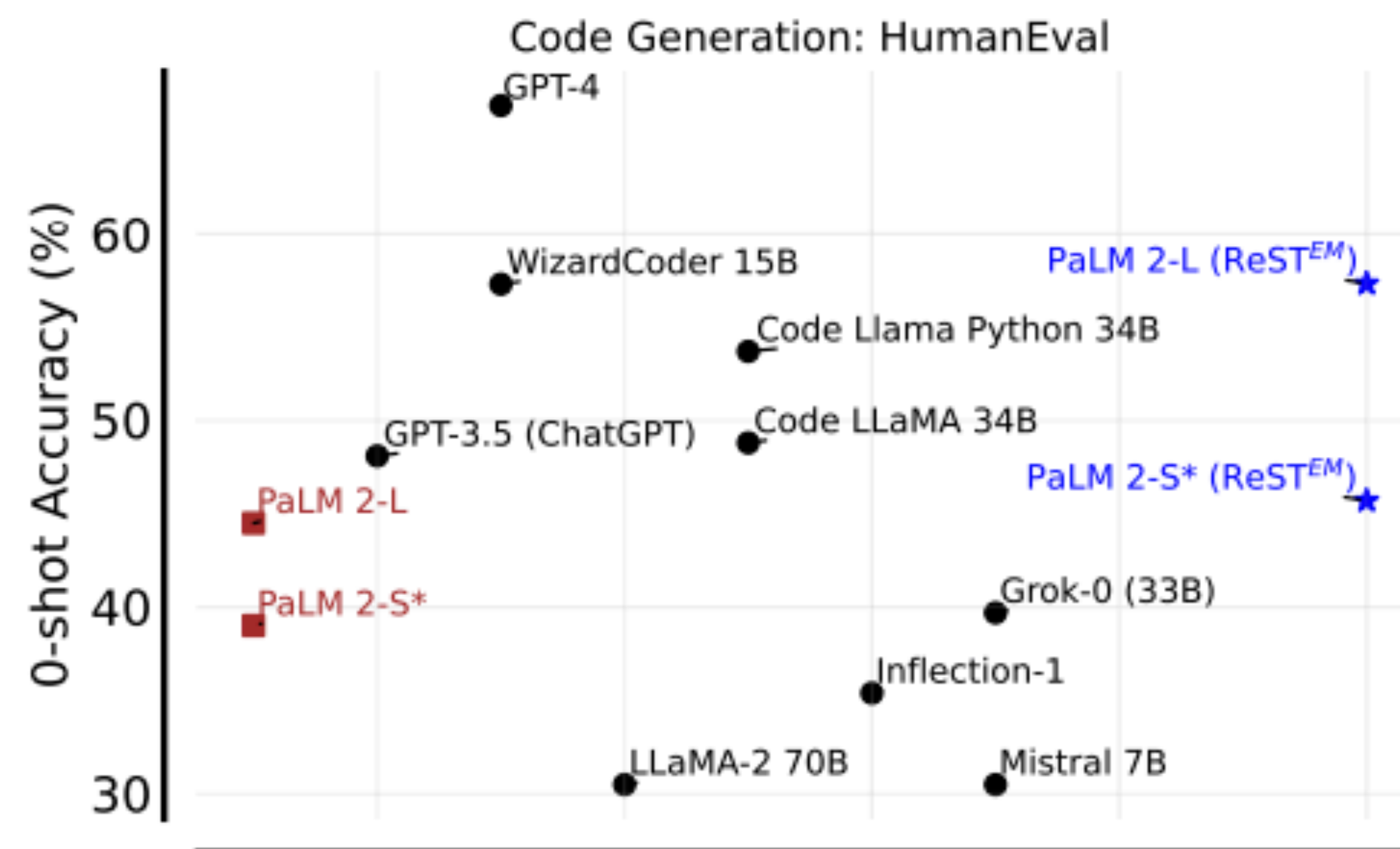
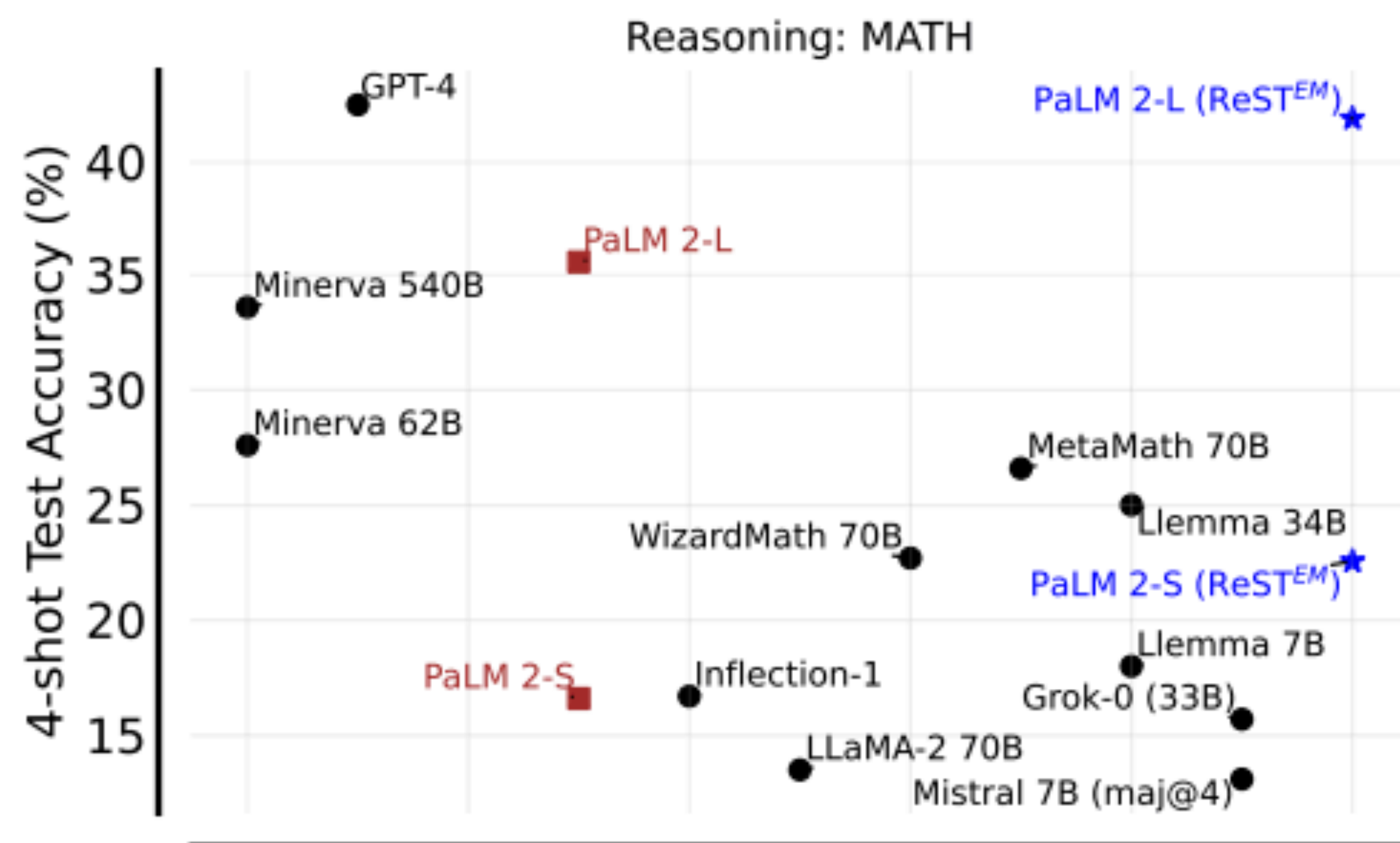
## Evaluation:

- Pass@1 (direct generation)
- Pass@k / majority voting for diversity

# Results



# Results



# Key Observations

## Significant Boost Over Human Fine-Tuning:

- On MATH, ReST<sup>EM</sup> surpasses supervised fine-tuning (SFT) with human-written solutions.
- Gains are bigger for larger models (e.g., PaLM 2-L).

## Multiple Iterations:

- MATH: More iterations → steady improvement until overfitting starts.
- APPS: 1st iteration yields the largest boost; further iterations can hurt (fewer training problems).

## Improved Diversity:

- Higher Pass@K (chance that at least 1 of K samples is correct).
- Better majority-voting accuracy.

## Difficulty Analysis:

- MATH subset shows the biggest gains on medium-to-hard problems.
- Exploiting multiple model-generated solutions yields richer training data

# Limitations

## **Dependence on Clear Correctness Signals**

- ReSTEM needs a well-defined reward check.
- Tasks without an automatic way to decide correctness are hard to handle.

## **Overfitting on Small Data**

- Iteratively fine-tuning on a limited set of problems can reduce generalization, as seen in APPS.

## **Possible “Reward Hacking”**

- If the correctness check is incomplete or simplistic the model might learn shortcuts or produce false positive

# Conclusion

## **Model-Generated Data Can Outperform Human Data**

- Especially in math and coding tasks, correctness checks enable scalable, high-quality self-training.

## **ReST<sup>EM</sup> Scales**

- Strong gains observed on larger models; iterative refinement outperforms single-step approaches.

## **Overfitting is a Concern**

- The number of iterations and dataset size both matter. Repeated re-training can degrade performance.

## **Broad Potential**

- No major regressions on general benchmarks; could be generalized to a wide range of tasks with reliable performance